

Modeling and Simulation of Fuzzy Logic Based Maximum Power Point Tracking (MPPT) for PV Application

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Article Info

Article history:

Received Jun 12th, 201x

Revised Aug 20th, 201x

Accepted Aug 26th, 201x

Keyword:

Maximum power point tracking

Fuzzy logic algorithm

Photovoltaic

Simulink

MPPT

ABSTRACT

This paper presents modeling and simulation of maximum power point tracking (MPPT) used in solar PV power systems. The Fuzzy logic algorithm is used to minimize the error between the actual power and the estimated maximum power. The simulation model was developed and tested to investigate the effectiveness of the proposed MPPT controller. MATLAB Simulink was employed for simulation studies. The proposed system was simulated and tested successfully on a photovoltaic solar panel model. The Fuzzy logic algorithm successfully tracking the MPPs and performs precise control under rapidly changing atmospheric conditions. Simulation results indicate the feasibility and improved functionality of the system.

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1. INTRODUCTION

The growing energy demand of the world and the tremendous risk of climate change associated with the use of fossil fuels have driven research and development of alternative energy sources that are clean, efficient, renewable and environmentally friendly. Among all renewable energy sources, solar power systems attract more attention because they have several advantages such as pollution-free, low maintenance costs and low operating costs. Their sources of energy, which is derived from solar energy, are also widely available and it is free [1-4].

In solar power system, the solar energy is directly converted into electrical energy by solar PV module. The main components of solar PV systems are solar cells made from semiconductor materials that have a photovoltaic effect, which serves to convert solar energy into direct current electricity. When exposed to sunlight, the solar panels will generate the direct current electricity, which is ready to supply power to the load.

Solar Panels do not need much maintenance and have no moving parts. The unfavorable issue with solar PV systems is the high installing cost and the variation of energy form the solar panel with environmental conditions. In order to attain the maximum efficiency from the solar panel, it is important to obtain the maximum available power at any operating condition. Also, the power distribution across the system has to be managed. Storage devices are used so that the energy is stored or supplied according to the availability of sufficient power and the load requirements [5].

The efficiency of solar cells depends on many factors such as temperature, irradiance, spectral characteristics of sunlight, dirt, shadow, and so on. Changes in insolation on panels due to fast climatic changes such as cloudy weather and increase in ambient temperature can reduce the photovoltaic (PV) array

output power. In other words, each PV cell produces energy pertaining to its operational and environmental conditions [6].

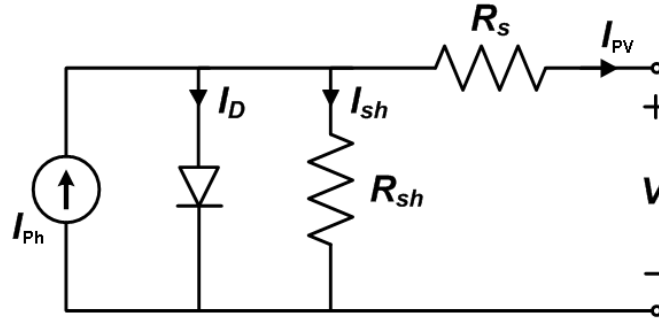


Figure 1. Solar Cell Equivalent Circuit

In addressing the poor efficiency of PV systems, some methods were proposed, among which is a new concept called “maximum power point tracking” (MPPT). All MPPT methods follow the same goal which is maximizing the PV array output power by tracking the maximum power on every operating condition.

2. SOLAR PHOTOVOLTAIC MODEL

The mathematical model of the PV cell can be developed by using equivalent circuit of PV Cell. The most common of PV cell model is the single diode circuit model that represents the electrical behavior of the pn-junction [4],[7-8]. Figure 1 shows the single diode equivalent circuit model of Solar cell.

From the single diode equivalent circuit in Figure 1, the equation for the output current is given by:

$$I_{pv} = I_{ph} - I_D - I_{sh} \quad (1)$$

The current through the diode follow the Shockley diode equation:

$$I_D = I_O \left[e^{\left(\frac{qV_D}{nkT} \right)} - 1 \right] \quad (2)$$

$$I_{sh} = \frac{V_{sh}}{R_{sh}} \quad (3)$$

$$V_D = V_{pv} + I_{pv} R_s \quad (4)$$

where, I_{pv} is the PV output current, I_{ph} is the photocurrent, I_D is the diode current, I_{sh} is the shunt current, I_O is the reverse saturation current, n is diode ideality factor, q is the electron charge, k is the Boltzmann constant, T is the absolute temperature, V_D is the voltage across diode and resistor R_{sh} , V_{pv} is the output terminal voltage, and R_s is the series resistance of the PV cells.

By substituting equation (2), (3) and (4) into the first equation, the characteristic equation of a PV cell, which relates solar cell parameters to the output current and voltage, is given by the following expression[1-2]:

$$I_{pv} = I_{ph} - I_O \left[e^{\left(\frac{q(V_{pv} + I_{pv}R_s)}{nkT} \right)} - 1 \right] - \frac{V_{pv} + I_{pv}R_s}{R_{sh}} \quad (5)$$

The nonlinear equation of PV characteristic actually depends on the solar irradiance and the cell temperature. As the references, the PV module manufacturers normally provided specified data at Standard Test Conditions where the irradiance is 1000W/m^2 and the cell temperature is 25°C [7-8].

In this paper, the ICA100 PV module was chosen for simulation setup. The electrical parameters are tabulated in table 1, and the characteristic curves are shown in Figure 2 and 3. Figure 2 illustrates the P-V

characteristic of the ICA100 module under different irradiance and Figure 3 illustrates the P-V characteristic under different temperature conditions.

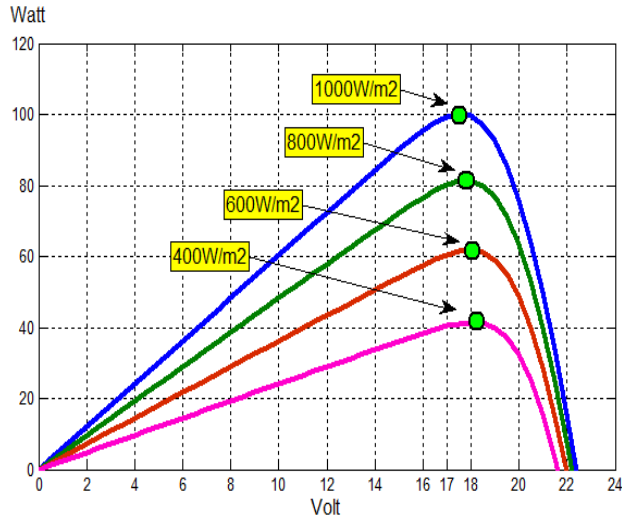


Figure 2. P-V characteristics at irradiance variation

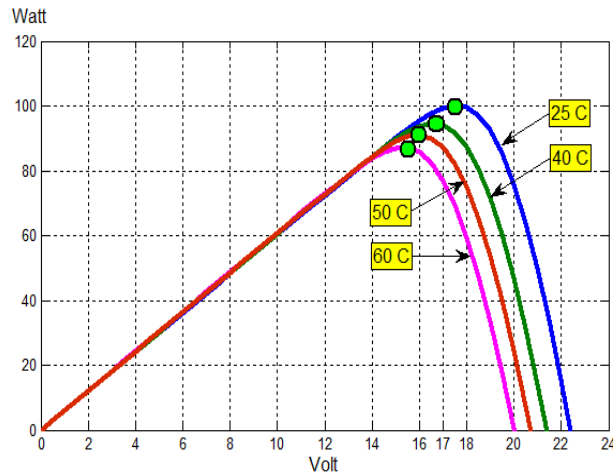


Figure 3. P-V characteristics at temperature variation

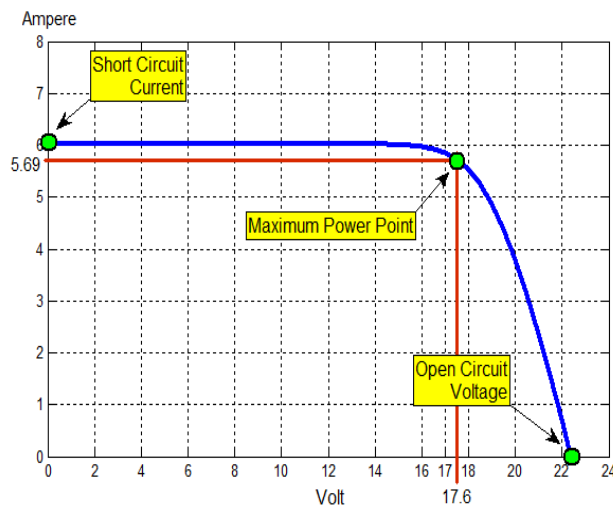


Figure 4. Current – vs – Voltage curve of PV module

Figure 4 shows the current-vs-voltage curve of the PV module. It gives an idea about the significant points on each I–V curve: open-circuit voltage, short-circuit current, and the operating point where the module performs the maximum power (MPP). This point is related to a voltage and a current that are V_{mp} and I_{mp} , respectively, and is highly dependent on solar irradiation and ambient temperature [7].

Table 1. Specification of ICA100 PV Module

Parameters	Symbol	Value
Maximum power	P_{max}	100 W
Voltage at max power	V_{mp}	17.6 V
Current at max power	I_{mp}	5.69 A
Open circuit voltage	V_{oc}	22.4 V
Short circuit current	I_{sc}	6.03 A
Number of Series Cells	N_s	36
Number of Parallel Cells	N_p	1

3. MAXIMUM POWER POINT TRACKING (MPPT)

The Maximum Power Point Tracking (MPPT) is an algorithm that included in charge controllers used for extracting maximum available power from PV module under certain conditions. The MPPT algorithm moves the electrical operating point of the PV modules to its Maximum Power Point, so that the modules are able to deliver maximum available power.

The voltage at which PV module can produce maximum power point is called maximum power voltage (or peak power voltage). The Maximum Power Point of PV module varies with solar radiation, ambient temperature and solar cell temperature. From Power – vs – Voltage curve in Figure 5, the ICA100 PV module produces power with maximum power voltage of around 17.6 V when measured at a cell temperature of 25°C, it can drop to around 16 V on a very hot day and it can also rise to 19 V on a very cold day.

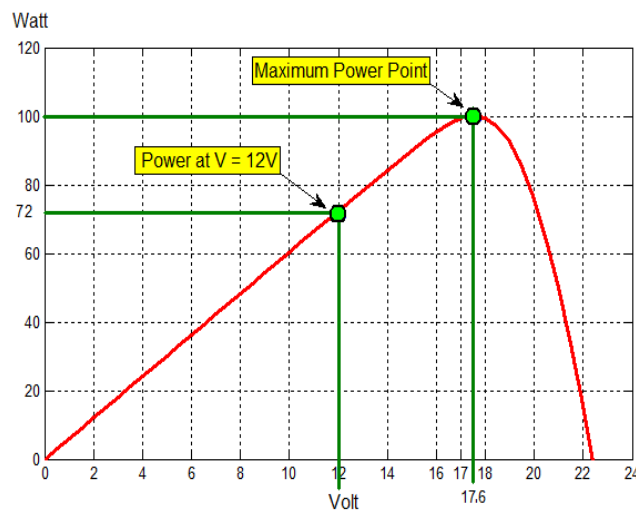


Figure 5. Power – vs – Voltage curve of PV module

When a load is directly connected to the PV panel, the PV panel operating point is usually not at peak power. In Figure 5, it is clear when a 12V dc load is directly connected to the PV panel, the PV output power is only 72W, which is less than the maximum available power of PV module.

The impedance seen by the PV panel derives the electrical operating point of the solar PV panel. By varying the impedance seen by the PV panel, the electrical operating point can be moved towards peak power point. Since solar PV panels are DC devices, DC-DC converters might be used to transform the impedance of

solar panel circuit to the load circuit. Changing the duty ratio of the DC-DC converter results in the impedance seen by the panel being changed. In order to maximize the extraction power of solar photovoltaic systems, the DC-DC converter must be able to track a particular duty ratio that make the operating point will be at the maximum power point (MPP).

There are a large number of algorithms that are able to track the MPPs. Some of them are simple, such as voltage and current feedback control base, while some are more complicated, such as hill climbing method, Perturbation and Observation (P&O) method and Incremental Conductance method. They vary in complexity, sensor requirement, speed of convergence, cost, range of operation, popularity, ability to detect multiple local maxima, and their applications [9-11].

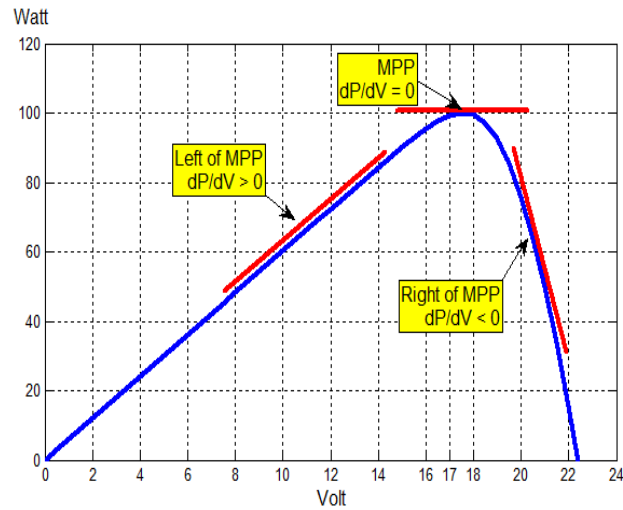


Figure 6. Basic idea of the MPPT method

Most of MPPT method focuses directly on power variations and the slope of the P–V characteristic curve. In Figure 6, we can see that the MPP is located at the peak of the Power – vs – Voltage curve of PV module. Here the value of PV power is maximum. Figure 6 shows that the slope of the PV array power curve, dP/dV , is zero at the MPP, positive on the left of the MPP and negative on the right-hand side of the MPP. The basic equations of this method are as follows :

$$\frac{dP}{dV} = 0, \quad \text{at MPP} \quad (6)$$

$$\frac{dP}{dV} > 0, \quad \text{left of MPP} \quad (7)$$

$$\frac{dP}{dV} < 0, \quad \text{right of MPP} \quad (8)$$

where P and V are the PV array output power and voltage, respectively.

4. MPPT FUZZY LOGIC CONTROLLER

Fuzzy Logic has been used for tracking the Maximum Power Point (MPP) of PV module because it has the advantages of being robust, relatively simple to design and does not require the knowledge of PV exact model. Fuzzy logic control generally consists of three basic componens: fuzzification module, fuzzy inference engine, and defuzzification module, as shown in Figure 7.

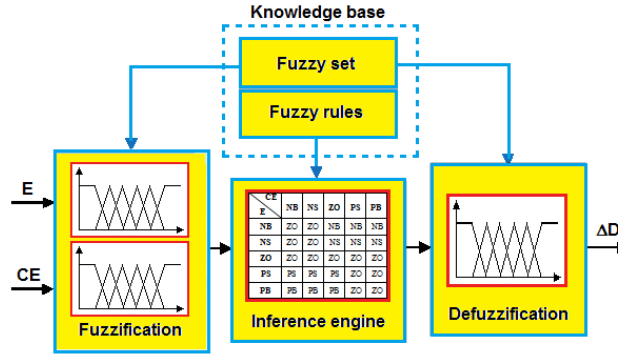


Figure 7. Structure of fuzzy logic controller

4.1. Fuzzification

During fuzzification, numerical input variables are converted into linguistic variable based on a membership function. For this MPPT, the actual voltage and current of PV module measured continuously and the power can be calculated as $P=V \times I$. The control is determined based on satisfaction of two proposed input control variable, namely the error E (which represents the slope of P-V characteristic) and change of error CE at the instant sampling k. The variable E and CE are expressed as follows:

$$E(k) = \frac{P(k) - P(k-1)}{V(k) - V(k-1)} \tag{9}$$

$$CE(k) = E(k) - E(k-1) \tag{10}$$

where P(k) is the power and V(k) is voltage of PV module. The change in duty ratio (ΔD) of the DC-DC Converter is used as the output of the controller. Therefore, the control is done by changing this duty ratio according to the slope E(k) in order to track the operation point to the optimal point where the slope is zero.

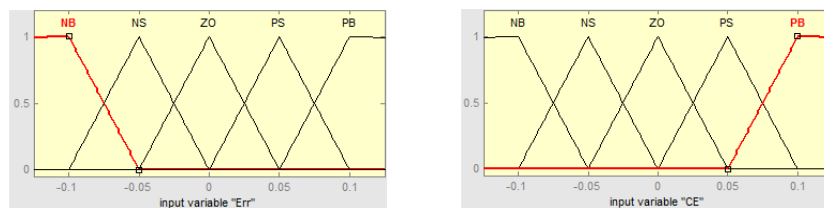
As shown in Figure 7, the input variables of the fuzzy controller (E, CE) are converted to the linguistic variables such as PB (positive big), PS (positive small), ZO (zero), NS (negative small), and NB (negative big) using basic fuzzy subset. Figure 8 shows the membership grades of five basic fuzzy subsets for input and output variables.

4.2. Inference Engine

The inference engine applies a rule to the fuzzy input to determine the fuzzy output. Therefore, before the rule can be evaluated, the real input value must be fuzzified to obtain an appropriate linguistic value. Table 2 shows the fuzzy controller rule table, where all the matrix entries are fuzzy sets of the error (E), the change of error (CE) and the change of duty ratio (ΔD) to converter.

The rule table in table 2 contain 25 rules of fuzzy controller. These rules are employed to control the DC-DC converter so that the MPP of the PV module is reached.

The main idea of the rules are to bring the operation point of PV module to the MPP by increasing or decreasing the duty ratio of DC-DC Converter depending on the position of the operation point from the MPP.



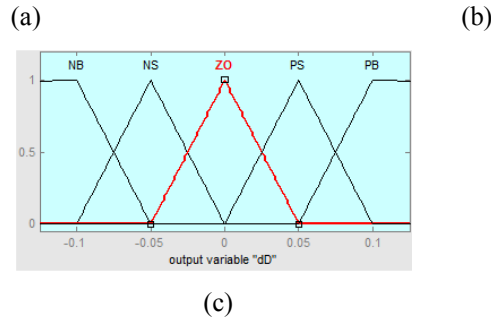


Figure 8. Membership function for (a) Input E, (b) Input CE, (c) Output ΔD

4.3. Defuzzification

Since the DC-DC converter require a precise control signal D at its entry, it is necessary to transform the output of fuzzy controller from fuzzy information into deterministic information. This tranformation is called defuzzification. In the defuzzification stage, the fuzzy logic controller output is converted from a linguistic variable to a numerical variable.

Defuzzification can be performed normally by two algorithms; Center of Area (COA) and the Max Criterion Method (MCM). The most widely used defuzzification method is the determination of the center of gravity (COA) of the final combined fuzzy set.

The final combined fuzzy set is defined by the unification of all outputs of the fuzzy rule set, using the maximum aggregation method. The center of gravity (ΔD) is computed by,

$$\Delta D = \frac{\sum_{j=1}^n \mu(\Delta D_j) \cdot \Delta D_j}{\sum_{j=1}^n \mu(\Delta D_j)} \quad (11)$$

and the actual duty ratio D is calculated by:

$$D(k) = D(k-1) + S_{\Delta D} \cdot \Delta D(k) \quad (12)$$

5. RESULT AND ANALYSIS

In order to evaluate the performance of the proposed Fuzzy Logic based MPPT controller, a simulation analysis was conducted. The simulation model was developed using MATLAB Simulink. The simulink model of PV system is shown as Figure 9. The PV module considered in the simulation is the ICA100.

Figure 9 shows the developed PV model system consisting of PV Solar Panel, Power Circuit and MPPT controller block diagram which is implemented using Fuzzy logic controller. The Fuzzy MPPT algorithm is presented in Figure 10. Figure 11 shows the simulation result of the Fuzzy MPPT algorithm response.

6. CONCLUSION

A modeling and simulation of fuzzy logic based Maximum Power Point Tracking for PV application is presented. The performance of the fuzzy logic MPPT algorithm system has been investigated. The simulation results show that the proposed fuzzy logic algorithm has a good and effective performance to generate maximum power from solar panels.

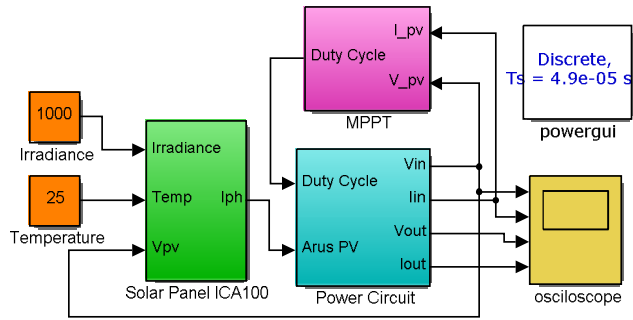


Figure 9. Simulink model of PV system

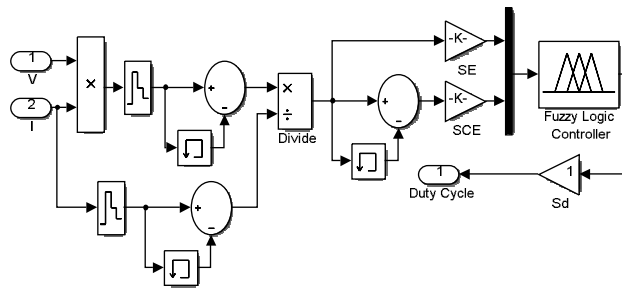


Figure 10. Block diagram of fuzzy MPPT algorithm

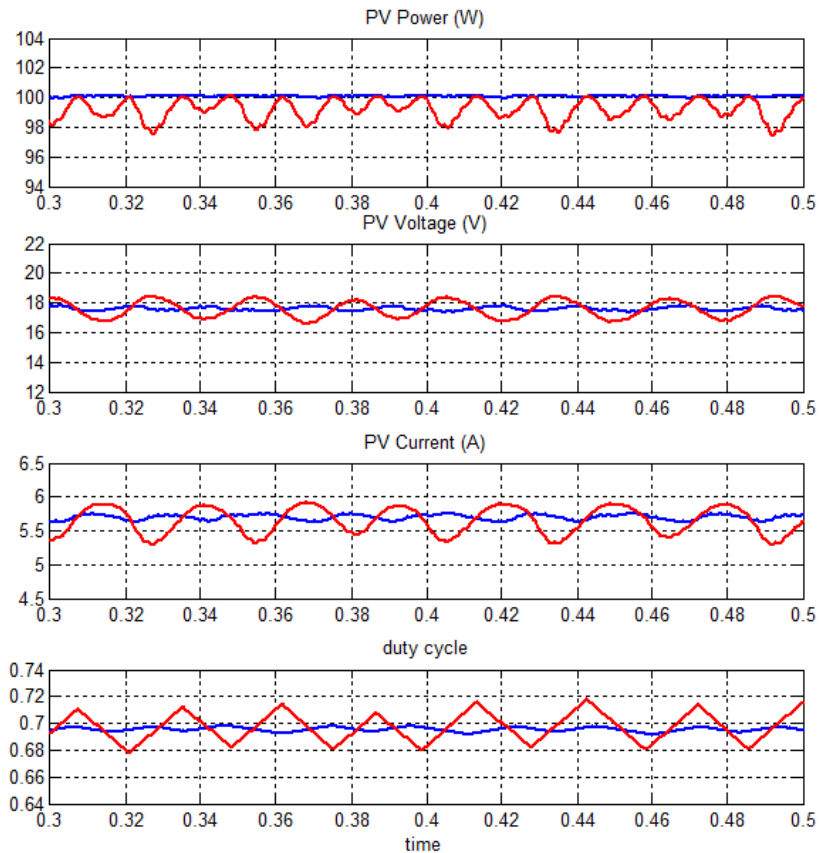


Figure 11. fuzzy MPPT algorithm response

ACKNOWLEDGEMENTS

The authors would like to thanks the Directorate General of Higher Education Indonesia (DIKTI) for the financial support via PUPIT Research Grant, and Lampung University for providing the facilities to conduct the research.

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